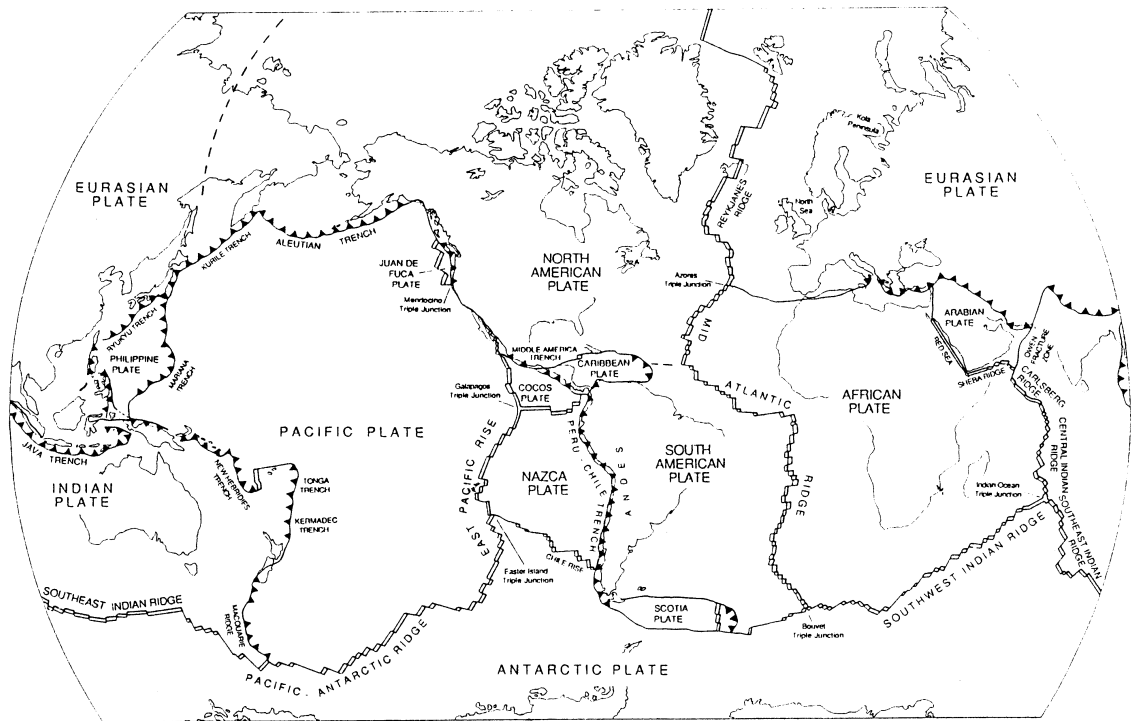


approx 100 km, not to horizontal scale



Thermal Diffusion

$\Delta H = \rho C_p \Delta T$ internal energy change per unit volume

$\rho = \text{mass density} \simeq 3.4 \times 10^3 \text{ kg/m}^3$
 $C_p = \text{specific heat} \simeq 0.71 \text{ J/g/K}$
} for mantle silicate rocks

Heat flows down temperature gradients:

$Q = k \frac{\partial T}{\partial z} = \text{heat flux}$ Fourier's Law, 1D
 $k = \text{thermal conductivity} \simeq 2.5 \text{ W/m/K}$

Energy balance: A = heat production per unit volume

$$\rho C_p \frac{\partial T}{\partial t} = \frac{\partial Q}{\partial z} + A \quad \text{1D, no motion}$$

$$\rho C_p \frac{\partial T}{\partial t} + \rho C_p v_z \frac{\partial T}{\partial z} = \frac{\partial Q}{\partial z} + A \quad \text{1D, with motion}$$

$$\rho C_p \left(\frac{\partial T}{\partial t} + \vec{v} \cdot \vec{\nabla} T \right) = -\vec{\nabla} \cdot \vec{q} + A \quad \text{3D, with motion}$$

Fourier's Law (3D): $\vec{q} = -k \vec{\nabla} T$

Thermal diffusion equation:

$$\frac{dT}{dt} = \kappa \nabla^2 T + A$$

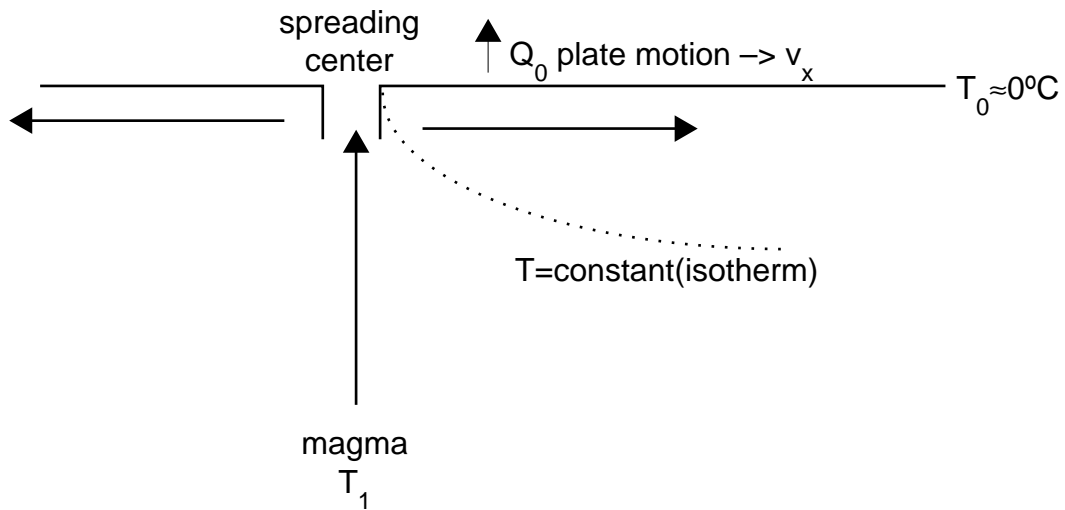
$\kappa = k / \rho C_p \simeq 10^{-6} \text{ m}^2/\text{s} = \text{thermal diffusivity}$

$$\frac{d}{dt} = \frac{\partial}{\partial t} + \vec{v} \cdot \vec{\nabla} = \text{material derivative}$$

$\vec{v} \cdot \vec{\nabla}$ is the advective term.

Cooling of Oceanic Lithosphere, I

Consider the 2D, steady-state problem:



This picture does not change with time!

Thermal diffusion equation: $\frac{dT}{dt} = \kappa \nabla^2 T + A$

$$\frac{dT}{dt} = \frac{\partial T}{\partial t} + \vec{v} \cdot \vec{\nabla} T \approx v_x \frac{\partial T}{\partial x} \quad \text{horizontal motion}$$

$$\kappa \nabla^2 T \simeq \kappa \frac{\partial^2 T}{\partial z^2} \quad \text{ignore horizontal conduction}$$

$$A \simeq 0 \quad \text{ignore heat production}$$

Define $\tau = x/v_x =$ seafloor age

$$\frac{\partial T}{\partial \tau} = \kappa \frac{\partial^2 T}{\partial z^2}$$

$$T = T(z, \tau)$$

Cooling of Oceanic Lithosphere, II

We need to solve

$$\frac{\partial T}{\partial \tau} = \kappa \frac{\partial^2 T}{\partial z^2}$$

subject to the boundary conditions:

$$\begin{aligned} T(z, 0) &= T_1 \\ T(0, \tau) &= T_0 \simeq 0^\circ C \end{aligned}$$

The solution is an error function:

$$T(z, \tau) = T_1 \operatorname{erf}(z/2\sqrt{\kappa\tau})$$

$$\operatorname{erf}(x) \equiv \frac{2}{\sqrt{\pi}} \int_0^x e^{-y^2} dy$$

The surface heat flux is:

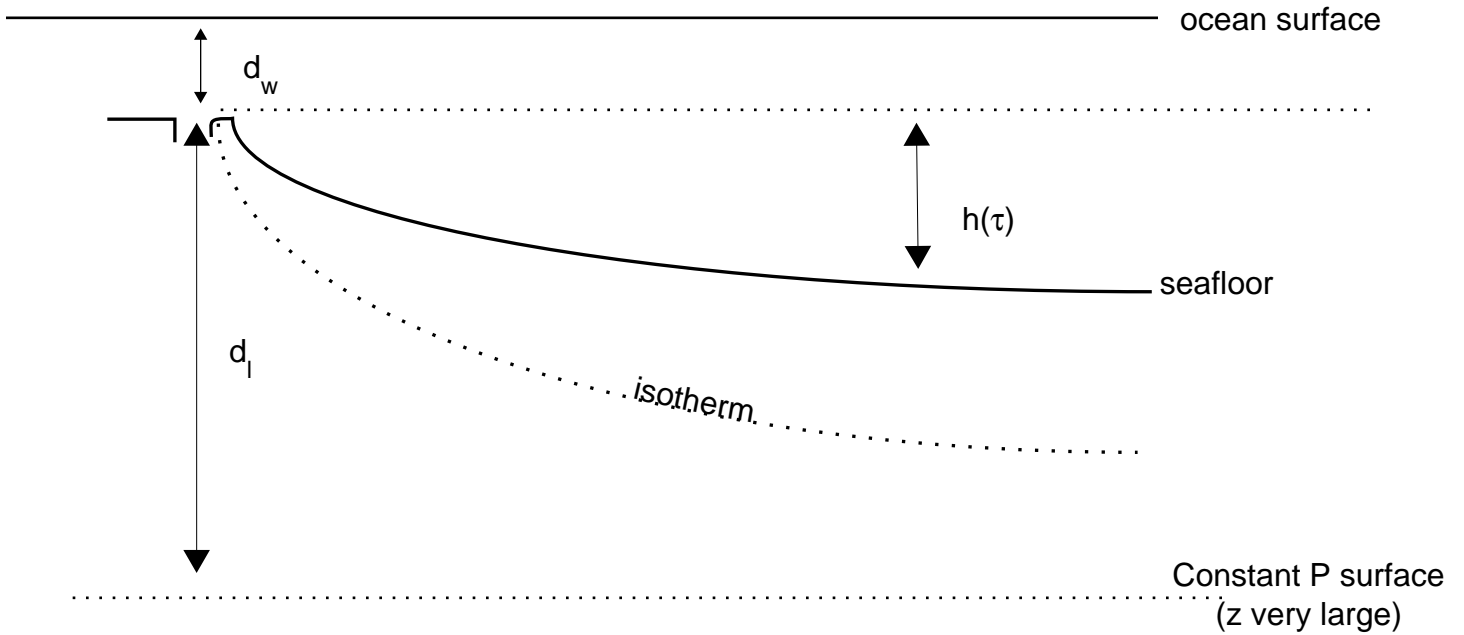
$$Q_0(\tau) = k \left(\frac{\partial T}{\partial z} \right)_0 = \frac{kT_1}{\sqrt{\pi\kappa\tau}} \sim \tau^{-1/2}$$

There will also be a topographic effect, because density depends on temperature:

$$\rho(T) = \rho_0(1 - \alpha T)$$

α = coefficient of thermal expansion $\simeq 3.3 \times 10^{-5}/K$

Cooling of Oceanic Lithosphere, III



Principle of Isostasy: at great depth, surfaces of constant pressure will be horizontal \implies mass above this “depth of compensation” will be approximately constant.

$$P(z) = \int_0^z \rho(\varphi)g(\varphi)d\varphi \simeq g_0 \int_0^z \rho(\varphi)d\varphi = \text{constant}$$

Mass balance:

$$M = \rho_w d_w + \rho_1 d_l \quad \text{at ridge crest}$$

$$\begin{aligned} M &= \rho_w(d_w + h) + \rho_1 \int_{d_w+h}^{d_w+d_l} (1 + \alpha(T_1 - T))dz \\ &= \rho_w(d_w + h) + \rho_1(d_l - h) + \alpha\rho_1 \int_{d_w+h}^{d_w+d_l} (T_1 - T)dz \end{aligned}$$

Equating:

$$(\rho_1 - \rho_w)h = \alpha\rho_1 \int_{d_w+h}^{d_w+d_l} (T_1 - T)dz \simeq \alpha\rho_1 \int_0^\infty (T_1 - T)dz$$

Cooling of Oceanic Lithosphere, IV

Isostasy thus implies:

$$h(\tau) = \left(\frac{\rho_1}{\rho_1 - \rho_w} \right) \alpha T_1 \int_0^\infty [1 - \operatorname{erf}(z/2\sqrt{\kappa\tau})] dz$$

But we know

$$\int_0^\infty [1 - \operatorname{erf}\left(\frac{x}{a}\right)] dx = a/\sqrt{\pi}$$

Therefore,

$$h(\tau) = \left(\frac{\rho_1}{\rho_1 - \rho_w} \right) \alpha T_1 2\sqrt{\frac{\kappa\tau}{\pi}}$$

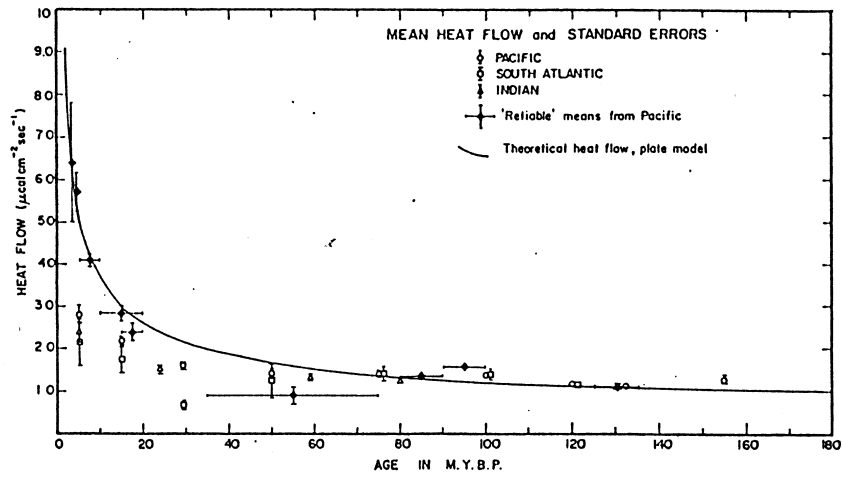
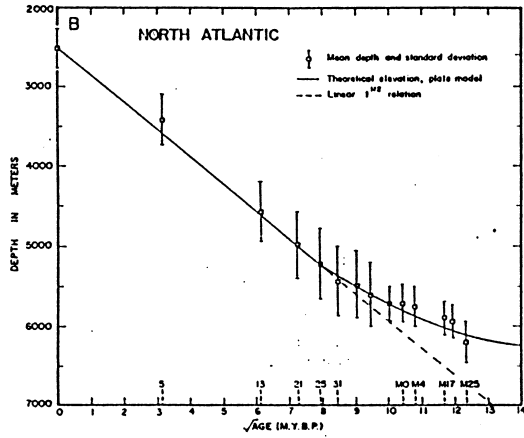
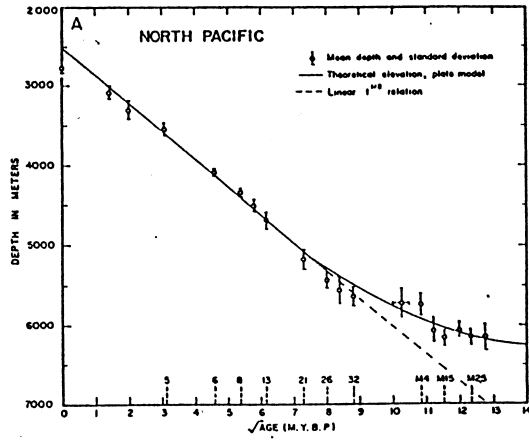
Assuming $T_1 = 1300^\circ C$, we obtain:

$$h(\tau) \simeq 385\sqrt{\tau}$$

$$[h]=\text{meters}, \quad [\tau]=\text{My}$$

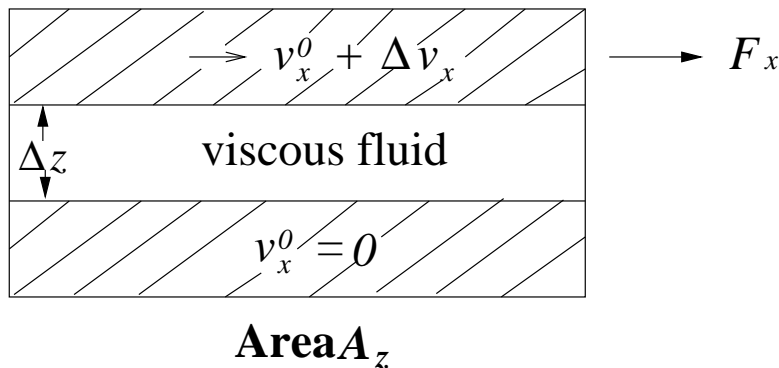
At the ridge crest, $d_w \simeq 2500$ m

Therefore, $d(\tau) \simeq 2500$ m + $340\sqrt{\tau}$ My



Newtonian Viscosity

Consider a thin layer of viscous material sandwiched between two rigid, parallel plates of area A :



In steady state we observe

$$\frac{F_x}{A_z} \sim \frac{\Delta v_x}{\Delta z}$$

Newtonian (linear) viscosity law:

$$\begin{aligned} \tau_{xz} &= \eta \frac{\partial v_x}{\partial z} \\ \tau_{xz} &= xz \text{ stress } [N/m^2 = Pa] \\ \frac{\partial v_x}{\partial z} &= xz \text{ strain rate } [s^{-1}] \\ \eta &= \text{dynamic viscosity } [Pas] \end{aligned}$$

Generalization to 3D: $x = x_1, y = x_2, z = x_3$

$$\begin{aligned} \tau_{ij} &= 2\eta \dot{\epsilon}_{ij} - p\delta_{ij} \\ \dot{\epsilon}_{ij} &= \frac{1}{2} \left(\frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} \right) \quad i, j = 1, 2, 3 \end{aligned}$$

Mantle Viscosity

For mantle rocks (peridotites), strain rate and stress are nonlinearly related:

$$\dot{\epsilon} \sim \tau^3$$

Moreover, the relationship is strongly temperature dependent.

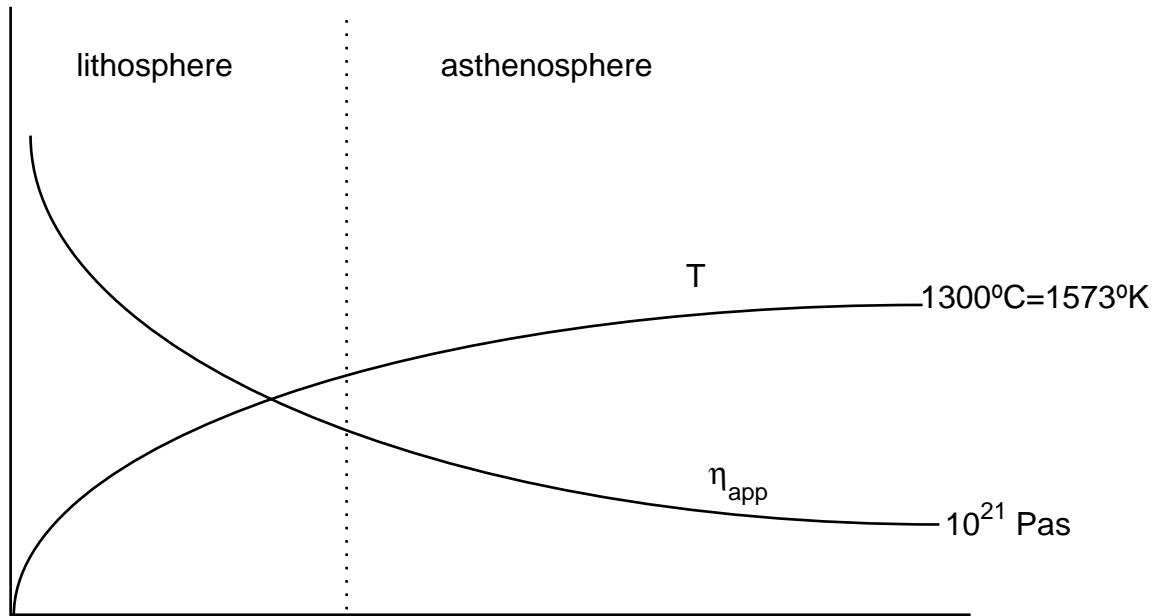
For dry olivine,

$$\dot{\epsilon} = C\tau^3 e^{-E^*/RT}$$

$$C \simeq 4.2 \times 10^5 \text{ MPa}^{-3} \text{ s}^{-1}$$

$$E^* \simeq 5.2 \times 10^5 \text{ J/mol} \text{ activation energy}$$

$$R \simeq 8.317 \text{ J/}^\circ\text{K/mol} \text{ gas constant}$$



$$\eta_{app} = \frac{e^{E^*/RT}}{C\tau_{ref}^2}$$

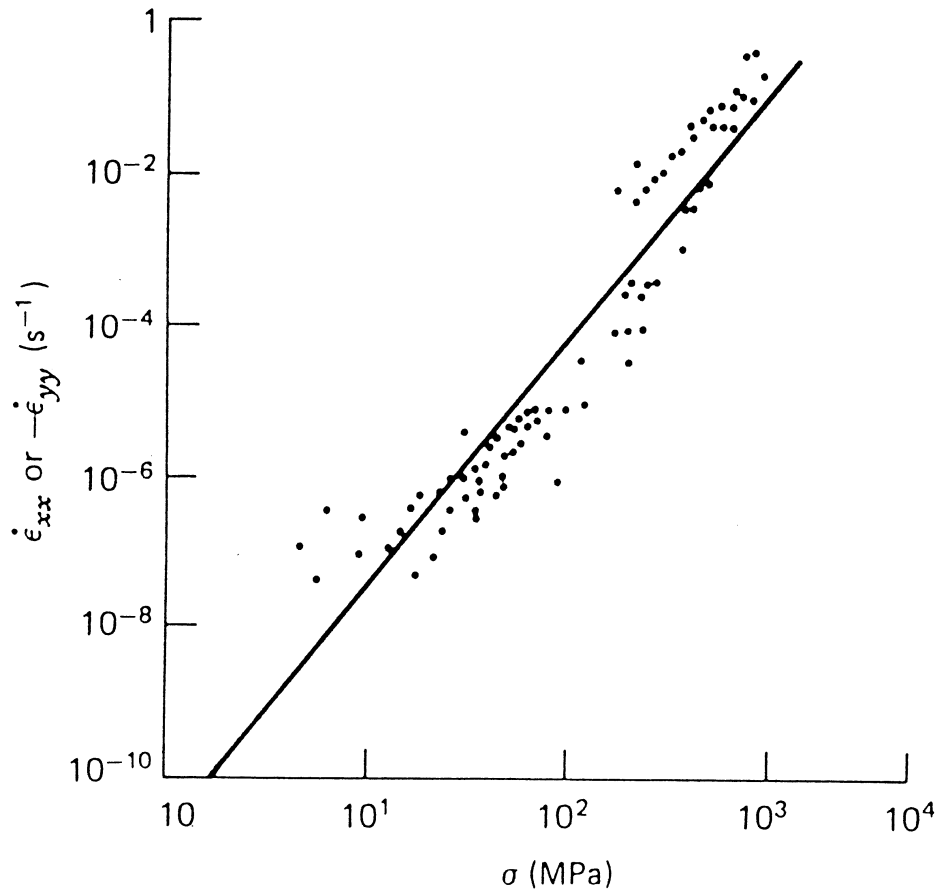
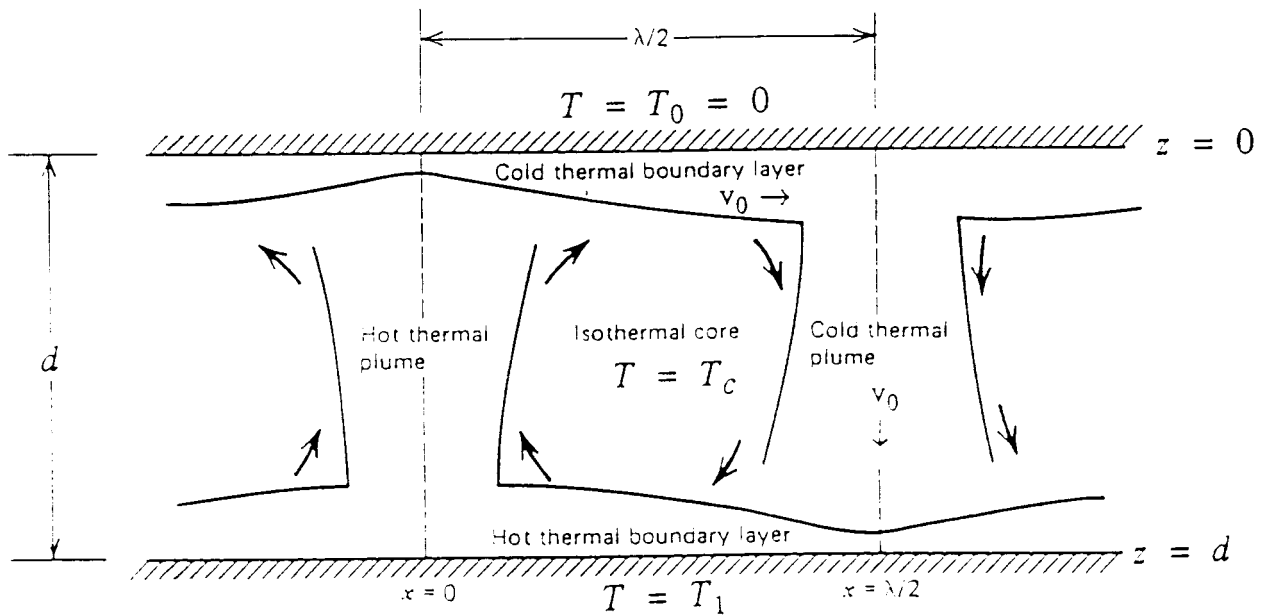


Figure 7-19 Observed dependence of strain rate on stress for olivine at a temperature of 1400°C. (After M. F. Ashby and R. A. Verall, Micromechanisms of flow and fracture and their relevance to the rheology of the upper mantle, *Philosophical Transactions of the Royal Society, London*, **288A**, 59–95, 1977.)

Analytical Toy Model of Mantle Convection

Approximations: “Boundary-Layer Theory” (2D)

- Periodic structure in x with wavelength λ
- Only driving forces are buoyancy forces of sinking slab and rising plume, which are symmetric
- Only resistive forces are viscous drags in isothermal core, which are symmetric



$$F_{slab} \simeq \begin{array}{l} \text{mass excess at "trench"} \\ \text{per unit length} \\ \rho_c \alpha T_c 2 \sqrt{\frac{\kappa \lambda}{2\pi v_0}} \end{array} \times \begin{array}{l} \text{gravitational} \\ \text{acceleration} \\ g \end{array} \times \begin{array}{l} \text{length} \\ \text{of slab} \\ d \end{array}$$

$$T_c = T_0 + (T_1 - T_0)/2 = T_1/2$$

$$F_{slab} = \rho_c g d \alpha T_1 \sqrt{\frac{\kappa \lambda}{2\pi v_0}}$$

To calculate the resistive forces due to viscous drag, we approximate the velocity gradients as constants:

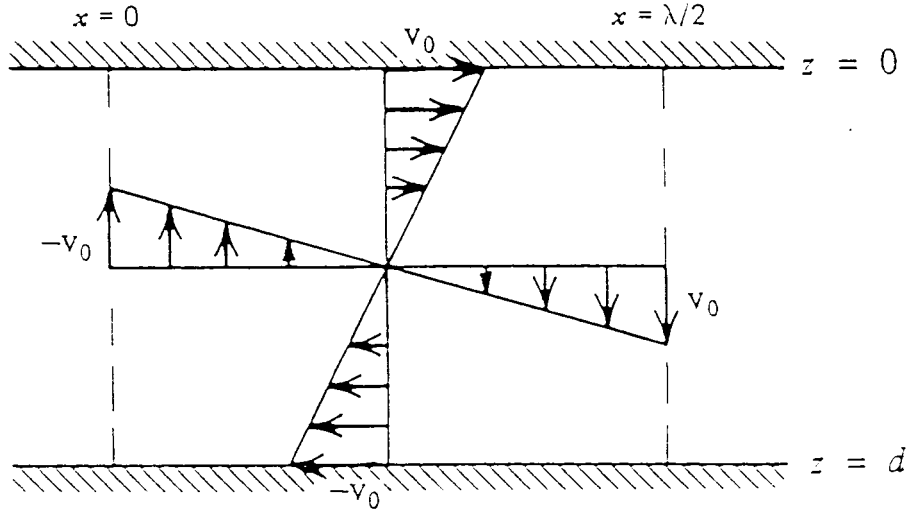


Plate:

$$v_x = v_0\left(1 - \frac{2z}{d}\right), \tau_{plate} = \eta \frac{\partial v_x}{\partial(-z)} \simeq \eta \frac{2v_0}{d}$$

Slab:

$$v_z = -v_0\left(1 - \frac{4x}{\lambda}\right), \tau_{slab} = \eta \frac{\partial v_z}{\partial x} \simeq \eta \frac{4v_0}{\lambda}$$

Force balance requires:

$$2F_{slab} = 2d\tau_{slab} + 2\left(\frac{\lambda}{2}\right)\tau_{plate}$$

Mass balance requires:

$$u_0 \frac{\lambda}{2} = v_0 d \implies \frac{\lambda}{2} = d \text{ if } u_0 = v_0$$