

## Precession, etc.

So far, have  $(C-A)$  in terms of  $I_2$  or  $C_2$   
 We have 5  $l=2$  terms, 6 terms in  $\frac{I}{r^3}$ .  
 What is value of  $C$ ?

Recall

$$C = I_{zz} = \iiint (x^2 + y^2) dM$$

Angular momentum

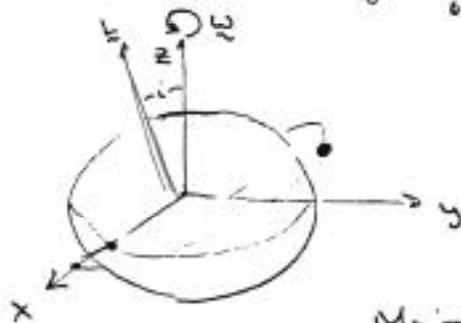
$$\vec{L} = \underline{\underline{I}} \vec{\omega}$$

$\underline{\underline{I}}$  inertial tensor  
 $\vec{\omega}$  rotation vector

to 1st order,  $\vec{\omega} \parallel \hat{z}$

$$L = C\omega$$

Recall satellite geodesy - earth exerts torque  $\vec{T}$   
 on satellites,  $\vec{L} = \underline{\underline{I}} \vec{\omega}$

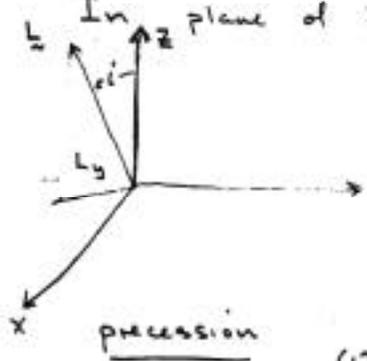


$$\vec{T}_x = \frac{3}{2} \frac{GMm a^2}{r^3} \frac{I_2}{I} \sin i \cos i$$

Newton's 3rd  $\Rightarrow$   
 $I$  acts on earth too!

Major components - lunar  
 solar

In  $I_{zz}$  plane of ecliptic



$$L_y = \omega C \sin i$$

$$\delta L_x = \vec{T}_x \delta t = \frac{2\pi}{\omega_p} \cdot \frac{3}{2} \frac{GMm_p a^2}{r_p^3} \frac{I_2}{I} \sin i \cos i$$

$$\text{Kepler} \Rightarrow \frac{GM}{r_p^3} = \omega_p^2, \quad I_2 = \frac{C-A}{Ma^2}$$

$$\omega_{PL} = \frac{1}{2\pi} \frac{\delta L_x}{L_y} = \frac{3}{2} \frac{C-A}{C} \frac{m_p}{M} \omega_p \cos i$$

Also - solar torque  
planet torques  $T \sim 26,000$  yrs

dynamic ellipticity

$$H = \frac{C-A}{C} = 0.00327364 = \frac{1}{305.47}$$

Note - not the same as  $f$   
 $H < f$

internal surface is not as elliptical as surface

core precession "different"

$$C = \frac{J_2}{H} \cdot Ma^2 = 0.3307 Ma^2$$

$$\left( \begin{array}{l} \text{Shell} - 0.6 Ma^2 \\ \text{uniform} - 0.4 Ma^2 \end{array} \right)$$

Other motions

1) Nutation ( $T_y, T_x$  vs  $\bar{T}_x$ )  
(case response different  $\Rightarrow$  coupling)

2) Chandler wobble (free nutation) (wobbly Earth)

$$\dot{\underline{L}} = \left( \underline{I} \dot{\underline{\omega}} \right) = \dot{\underline{I}} \underline{\omega} + \underline{I} \dot{\underline{\omega}} = 0$$

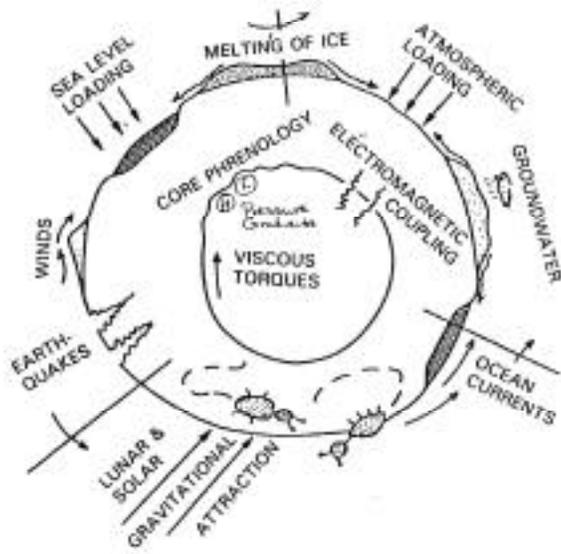
see Garland, section 1.3; Stacey, Section 3.3

3) Polar wander -

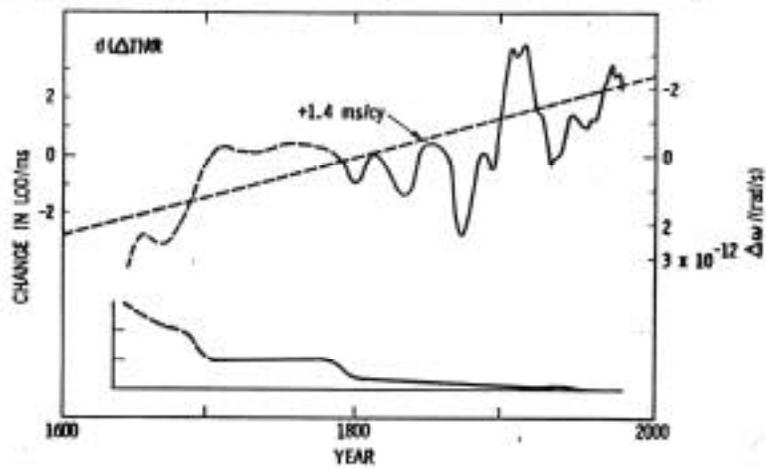
Due to  $l=2$  components of gravity

Precession + Nutation - pole moves relative to stars  
( $\underline{L}$  changes)

Chandler wobble + Polar wander - rotation axis moves relative to figure of earth.

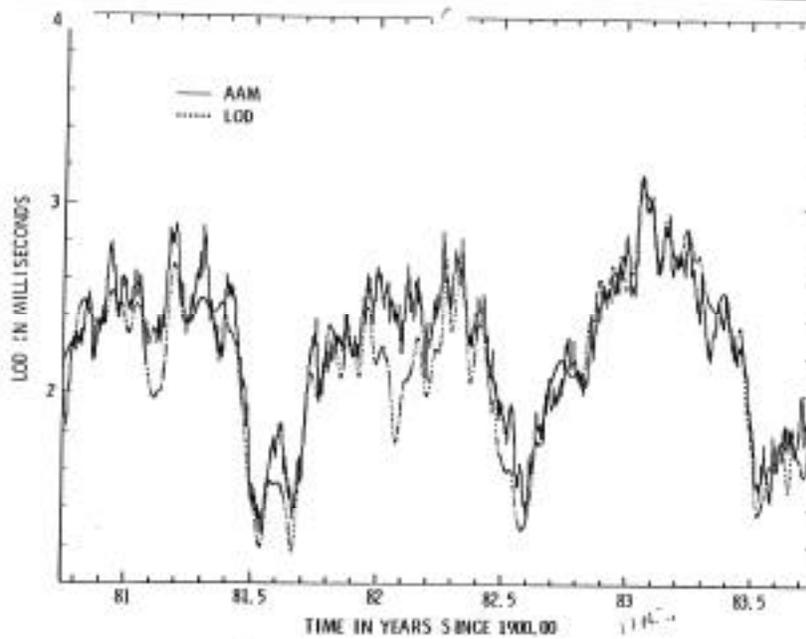
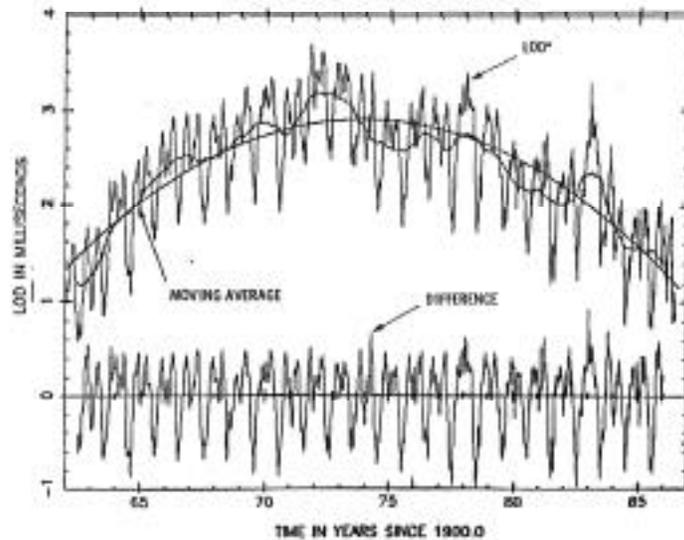


LENGTH OF DAY (LOD): 1620 TO 1980





COMBINED LOD\* WITH 365 DAY  
MOVING AVERAGE  
BEST FIT QUADRATIC



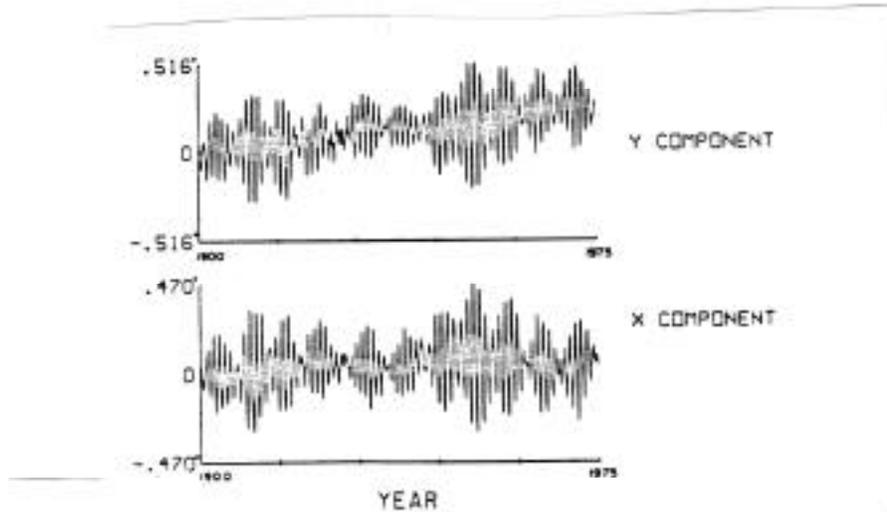


Figure 1. x and y components of the 1900-74 monthly variation-of-latitude data determined by the ILS-IPMS. They define the position of the instantaneous rotation pole in the CIO coordinate system.

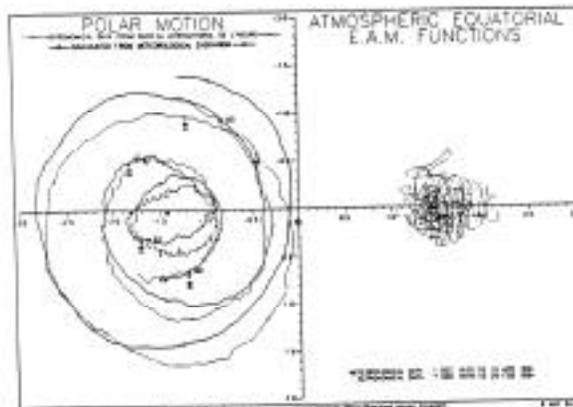


Figure 7

a) Observed polar motion as determined by the Bureau International de l'Heure compared with polar motion as inferred from the European Centre Meteorological data.  
 b) polar plot of the smoothed values. The units of both axis radians with  $10^{-6}$  rad equivalent to a displacement of about 6.4 m over the Earth's surface. (Hick, 1985 and private communication.)