

12.221 Field Geophysics 2011 – Lecture 1

Introduction to gravity – measurement and interpretation

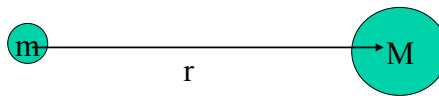
Reading: Lowrie, Fundamentals of Geophysics, pp. 73-95

see also Chapter 2 of 12.501 lecture notes (Rob van der Hilst)

<http://ocw.mit.edu/NR/rdonlyres/Earth--Atmospheric--and-Planetary-Sciences/12-201Fall-2004/E7A9DF78-ADC6-49A7-8812-1D8244939398/0/ch2.pdf>

(may be heavy going in places - skim global part, focus on gravity anomalies)

Gravity – simple physics



- Force: $f = GmM/r^2$
 $G = 6.67 \cdot 10^{-11} \text{ m}^3\text{kg}^{-1}\text{s}^{-2}$
Vector directed along r
- Acceleration of test mass: $g = GM/r^2$
- Potential energy: $U = -GmM/r$
- Gravitational potential $V = GM/r$

$$g = -\nabla \cdot V$$

Gravity – distributed density $\rho(x,y,z)$

- potential $\nabla^2 V = 4\pi G\rho$
- acceleration $g = -\nabla V$

$$V = 4\pi G \iiint_{\text{universe}} \frac{\rho(x,y,z)}{\sqrt{(x^2 + y^2 + z^2)}} dx dy dz$$

Measuring g places constraints on $\rho(x,y,z)$ (especially nearby)

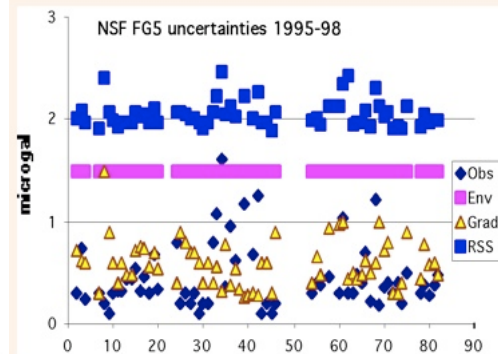
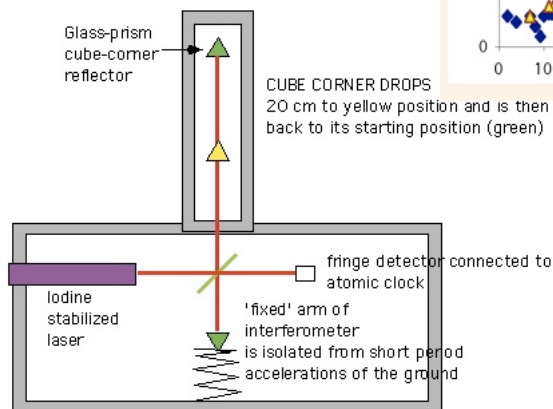
Measuring g does not constrain ρ directly (sphere \Leftrightarrow point mass)

$\rho(x,y,z)$ can be complicated

\Leftrightarrow simple physics, complicated interpretation

Interpretation (and effort justified) depend on accuracy of measurements - consider the trade-off judiciously!

Absolute gravimeter:
 $d = 1/2 gt^2$



60-120 drops/hr; 1-3 days

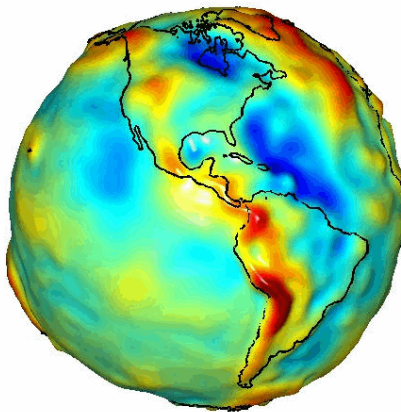
Environmental noise: water table variations, atmospheric pressure, tides, vibration, gravity gradient,

GRACE: Satellite-satellite range changes



http://www.csr.utexas.edu/grace/gallery/animations/grace_2/

GRACE “static” gravity variations



<http://www.csr.utexas.edu/grace/gallery/animations/ggm01/index.html>

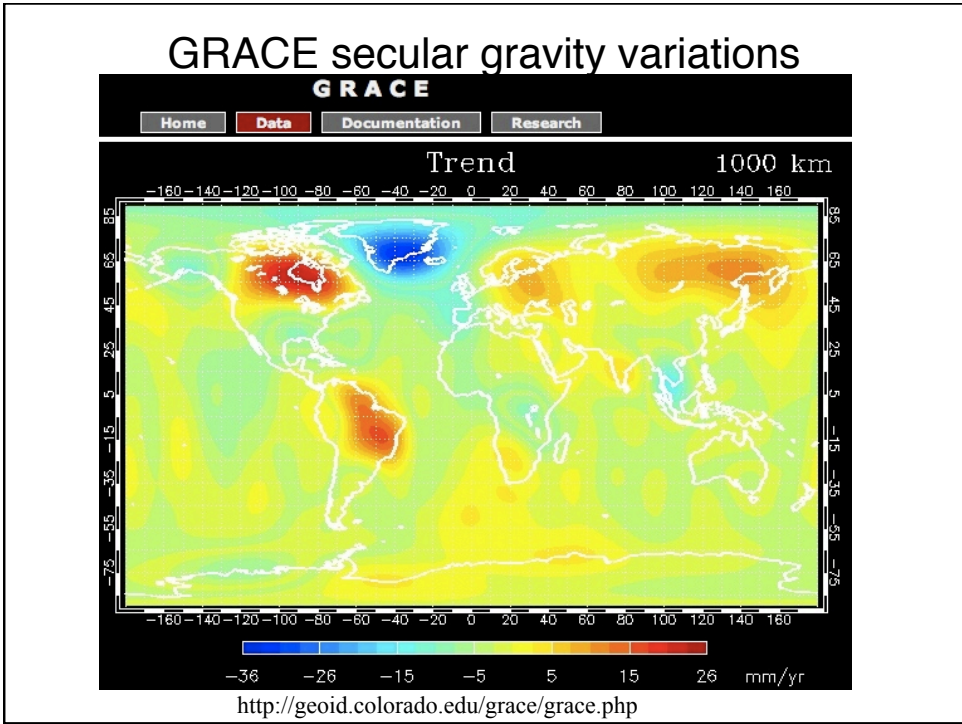
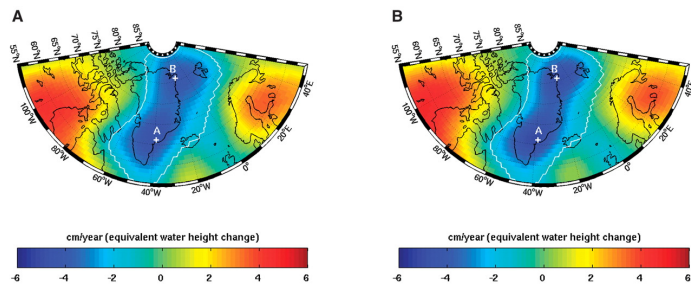


Fig. 2. (A) GRACE long-term mass rates over Greenland and surrounding regions during the period April 2002 to November 2005, determined from mass change time series on a 1-degree grid

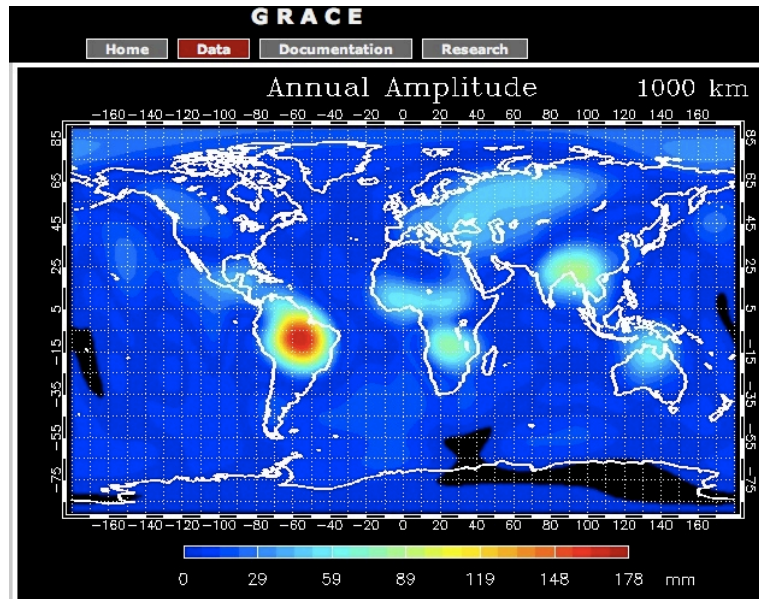


J. L. Chen et al., Science 313, 1958-1960 (2006)



Published by AAAS

GRACE annual gravity variations



<http://geoid.colorado.edu/grace/grace.php>

Measuring *variations in g*

- $f = mg = ku$
- $g \sim 9.8 \text{ m/s}^2$
- $g \sim 980 \text{ cm/s}^2$
(980 gals - Galileo)
- $\Delta g \sim 1 \text{ mgal}$ (10^{-6})
interesting
- Need good instrument,
good theory!

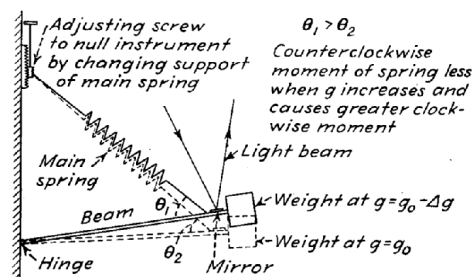
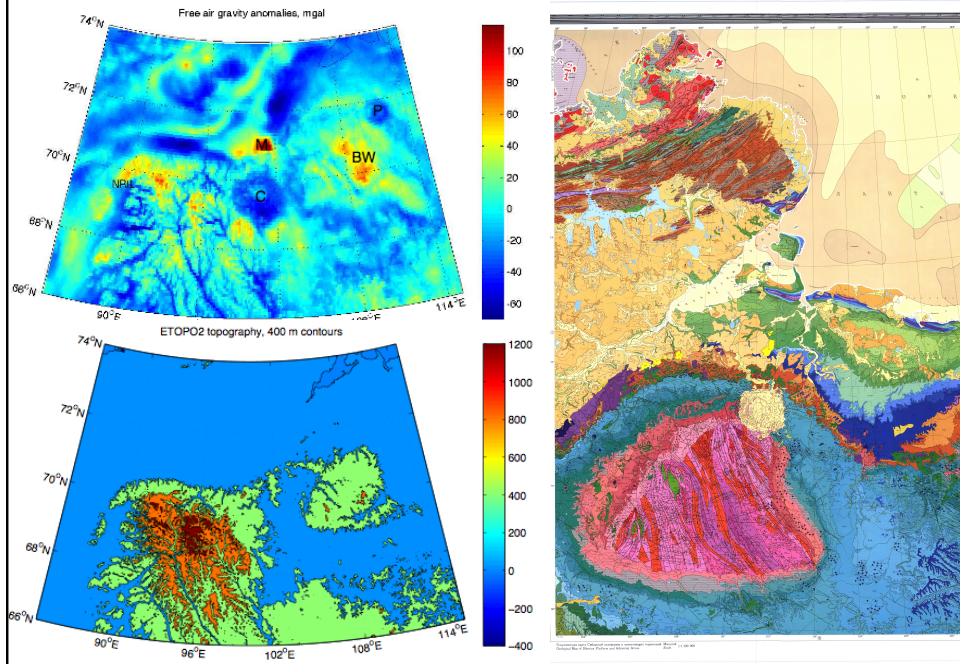
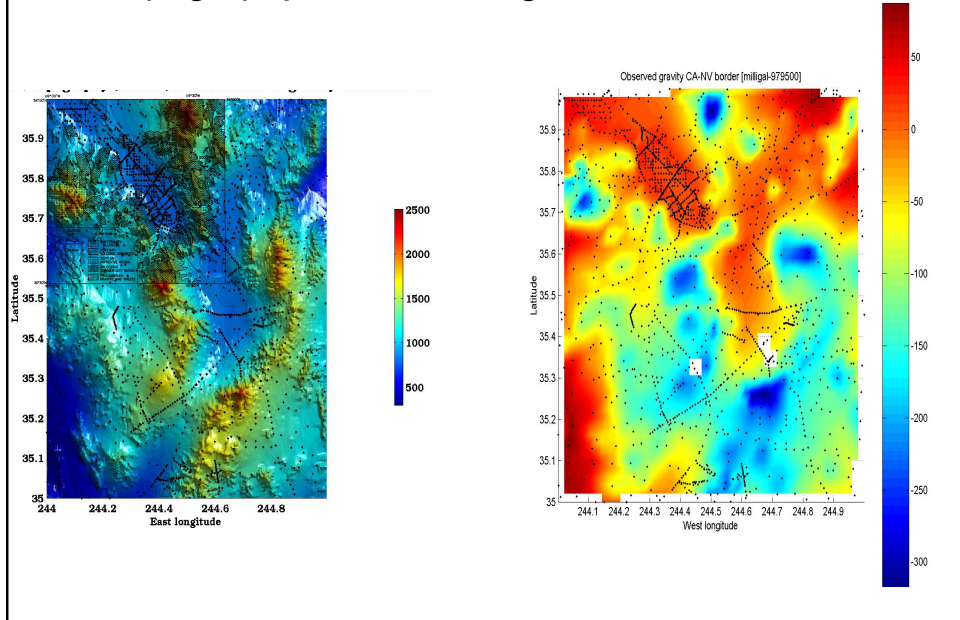


FIG. 4-12. LaCoste-Romberg gravimeter (schematic).

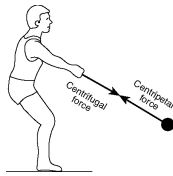
Example: Siberian Flood Basalts



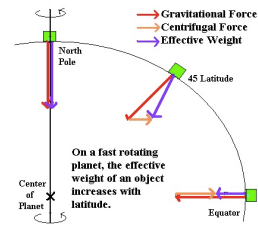
Topography & Observed g, Nevada-CA border



What causes these variations?



$$F_c = m\omega^2 r$$



www.answers.com/topic/centrifugal-force

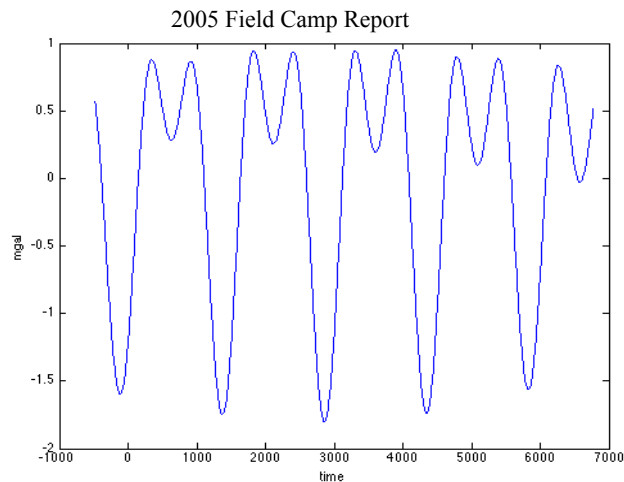
dinosaurtheory.com/solution.html

Spinning Earth -> centrifugal force, equatorial bulge
 centrifugal force => less g at equator, no effect at poles
 equatorial bulge (~elliptical)
 more mass near equator => g increases
 r larger at equator => g decreases
 Dependence of g on latitude (ϕ)

$$g(\phi) = 978032(1 + 0.0052789 \sin^2 \phi - 0.00000235 \sin^4 \phi) \text{ mgal}$$

$$dg/d\phi = 0.01 \text{ g} \sin \phi \cos \phi = 75 \text{ mgal/deg at } \phi = 30^\circ$$

Tides?



www.astro.oma.be/SEISMO/TSOFT/tsoft.html

What causes these variations?

$$g = GM/r^2$$

Elevation change $r \rightarrow r + h \Rightarrow g$ decreases (“free air” effect)

Free air effect:

$$g(r+h) = g(r) + (dg/dr) h$$

$$dg/dr = -2g/r = -0.307 \text{ mgal/m}$$

γ

Gravity anomalies

In general:

$$\Delta g = g_{\text{observed}} - g_{\text{theory}}$$

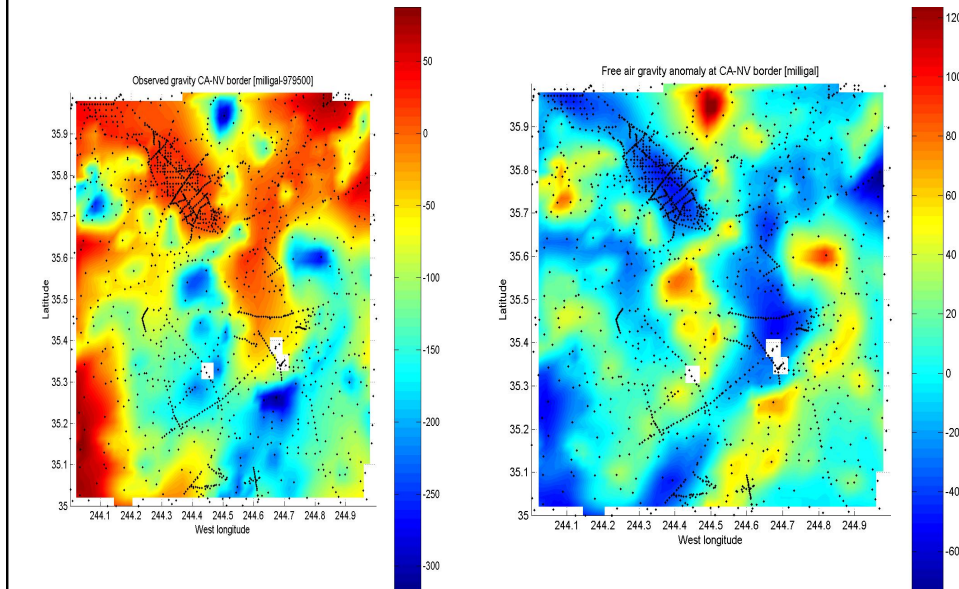
Free Air theory:

$$g_{\text{Free Air}} = g(\phi, h) = g(\phi) - 0.307 h$$

Free air anomaly:

$$\Delta g_{\text{faa}} = g_{\text{observed}} - g_{\text{Free Air}}$$

Observed g vs Δg_{FA}



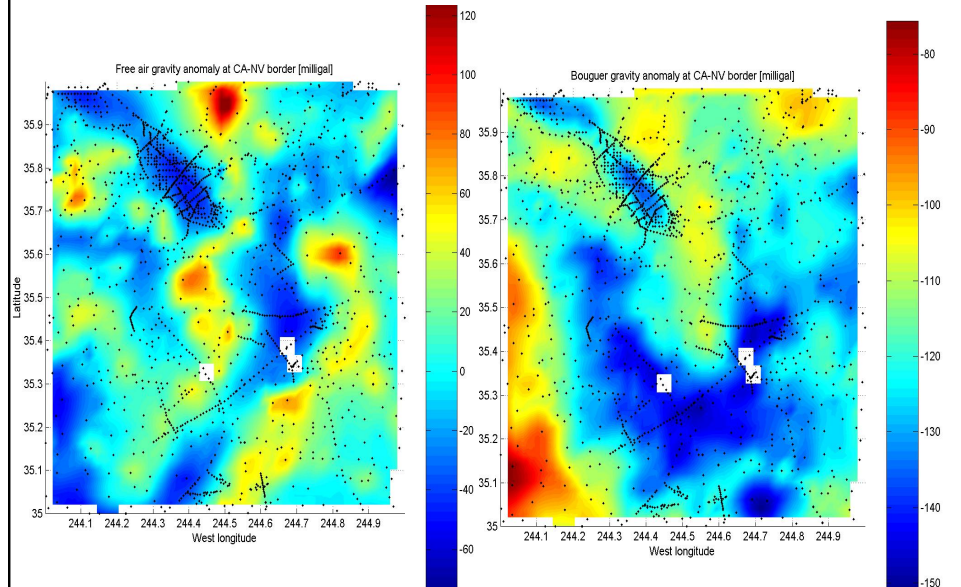
Bouguer gravity anomaly:
Mountains are not hollow!

Approximate as a sheet mass:

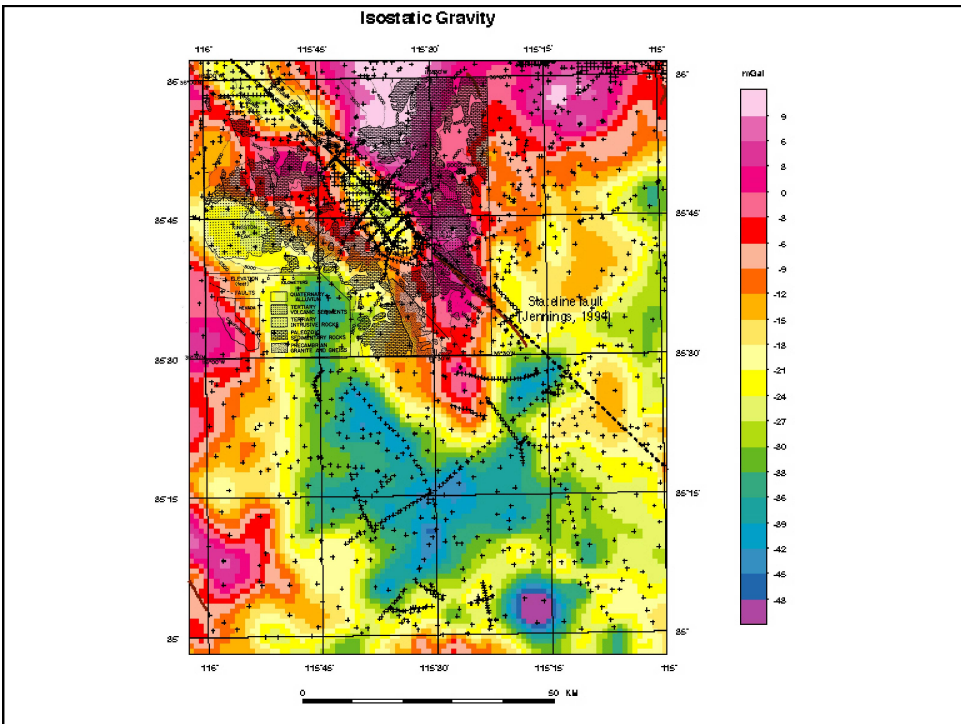
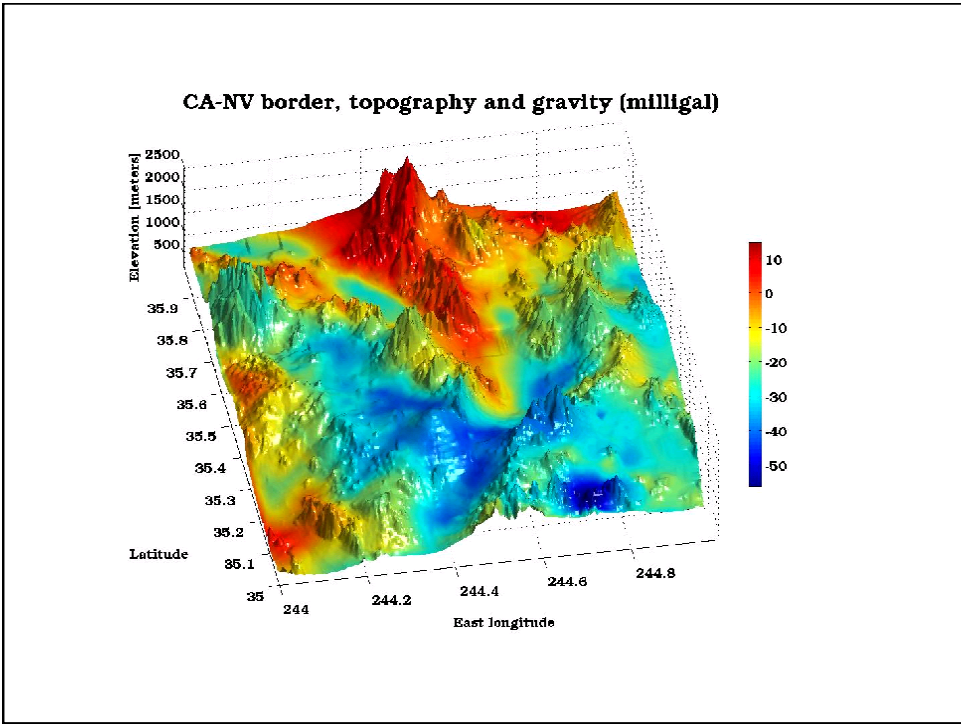
$$g_{\text{Bouguer}} = g_{\text{Free Air}} + 2\pi\rho Gh;$$

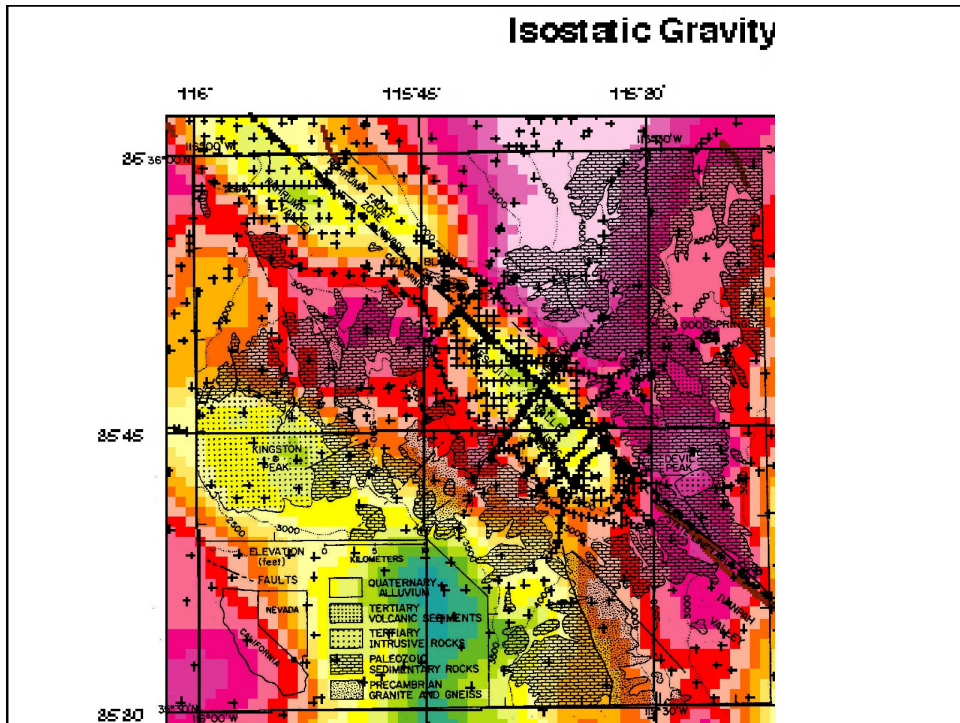
$$\text{for } \rho = 2.67, 2\pi\rho G = 0.112 \text{ mgal/m}$$

Δg_{FA} vs $\Delta g_{Bouguer}$



Isostasy: Mass in each column assumed to be equal

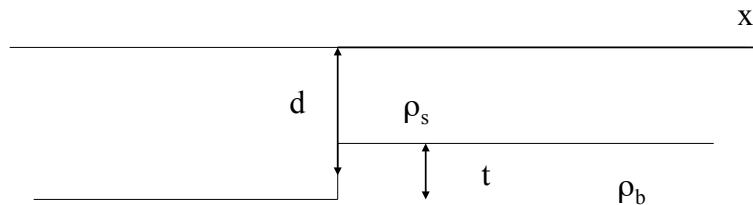




Step in basement topography

$$g = 2G(\Delta\rho)t[\pi/2 + \tan^{-1}(x/d)]$$

How big a step makes 1 mgal?



Terrain has an effect

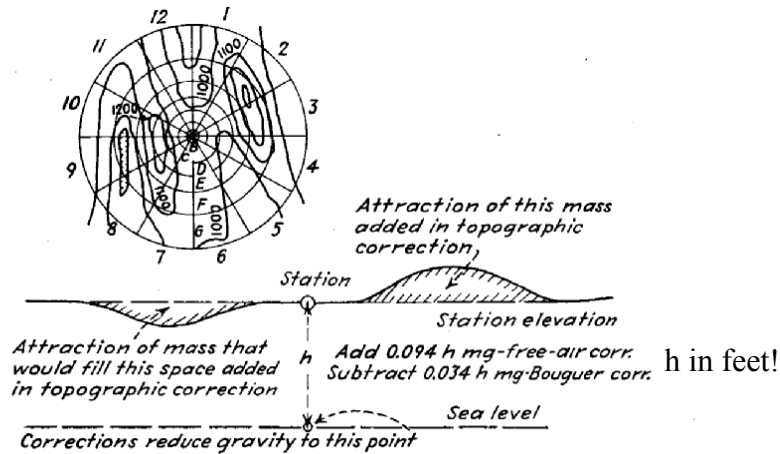


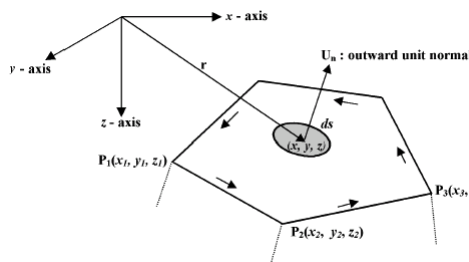
FIG. 3-2. Reduction of gravity values to the geoid. Inset shows typical zone chart used to obtain topographic corrections superimposed over contour map of area. Station is at elevation of 1,050 ft. Average elevation of zone 12-D, for example, is 1,020 ft. Hence topographic correction for this zone is 30 times the constant for the zone.

Computation of terrain & root using DEM – a new solution to a classic problem

New method for fast computation of gravity and magnetic anomalies from arbitrary polyhedra

Bijendra Singh* and D. Guptasarma*

GEOPHYSICS, VOL. 66, NO. 2 (MARCH-APRIL 2004); P. 521–526, 1 FIG.



Apply Gauss' theorem & dot product:

$$\mathbf{F} \cdot \mathbf{a} = -G\rho \iint (1/r) \mathbf{a} \cdot \mathbf{u}_n ds, \quad (1)$$

$$\begin{aligned} \mathbf{F} &= G\rho \iint (1/r)(\mathbf{r}/r) \cdot \mathbf{u}_n ds = G \iint (\rho \mathbf{r} \cdot \mathbf{u}_n)/r^2 ds \\ &= G \iint \sigma' ds/r^2. \end{aligned} \quad (2)$$

Thus, the attraction from a solid body, at the origin, is the same as that from a fictitious distribution of masses on its surface, the surface mass density (σ') everywhere taken to be equal to the product

$$\sigma' = \rho \mathbf{r} \cdot \mathbf{u}_n. \quad (3)$$

See <http://www.geo-online.org/manuscript/singh99063.pdf> for Matlab scripts for carrying out calculations

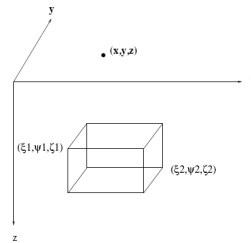
A parallel algorithm for three-dimensional gravity modelling and inversion



Diplomarbeit
 vorgelegt von
 Dror-John Röcher
 Bochum, April 2002

Right rectangular prism

$$g = -f\rho \int_{\xi_1}^{\xi_2} \int_{\eta_1}^{\eta_2} \int_{\zeta_1}^{\zeta_2} \frac{z - \zeta}{r^3} d\xi d\eta d\zeta$$



Formula 2.8 has been derived by many re

overview). According to them Sorokin (1951) derived the following form:

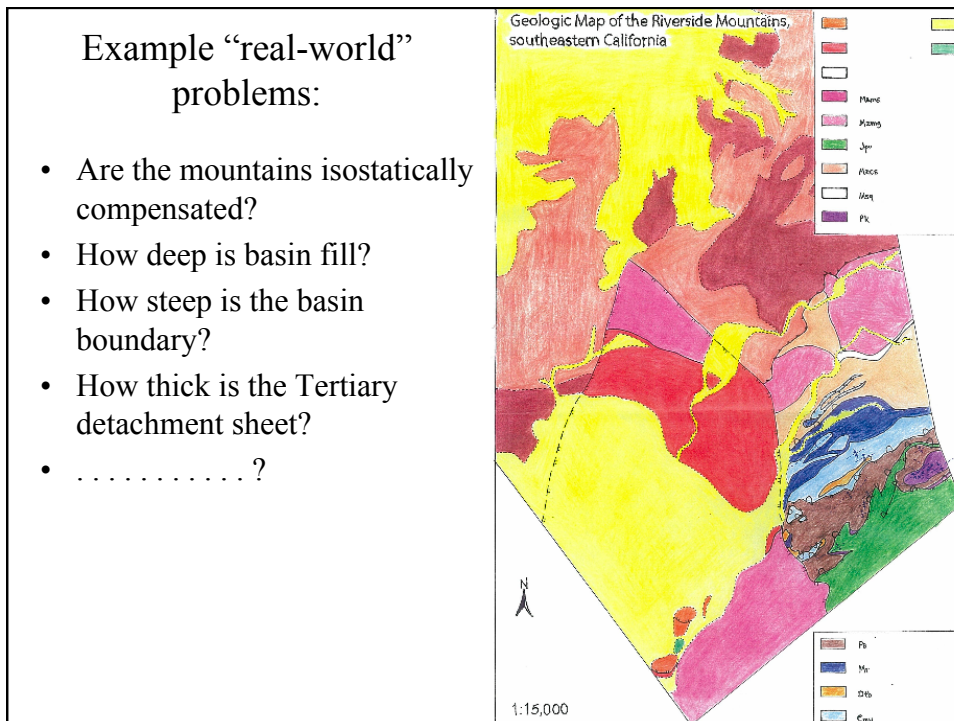
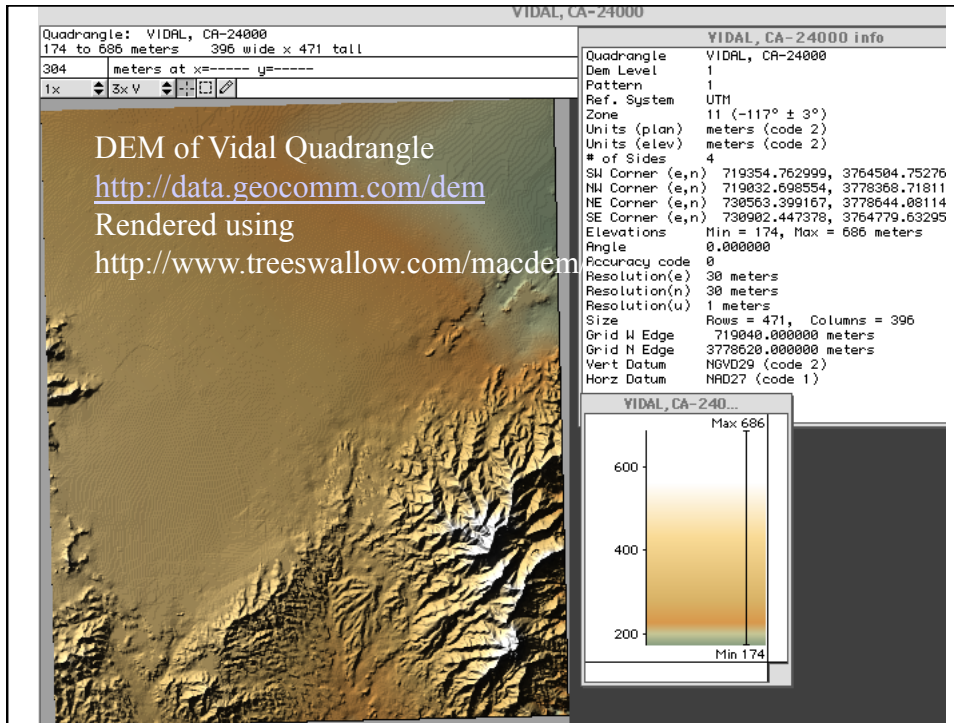
$$g = -f\rho \sum_{i=1}^2 \sum_{j=1}^2 \sum_{k=1}^2 \mu_{ijk} \left[x_i \ln(y_j + r_{ijk}) + y_j \ln(x_i + r_{ijk}) + z_k \arctan \frac{z_k r_{ijk}}{x_i y_j} \right] \quad (2.9)$$

where $x_i = x - \xi_i$, $y_i = y - \eta_i$, and $z_k = z - \zeta_k$, and

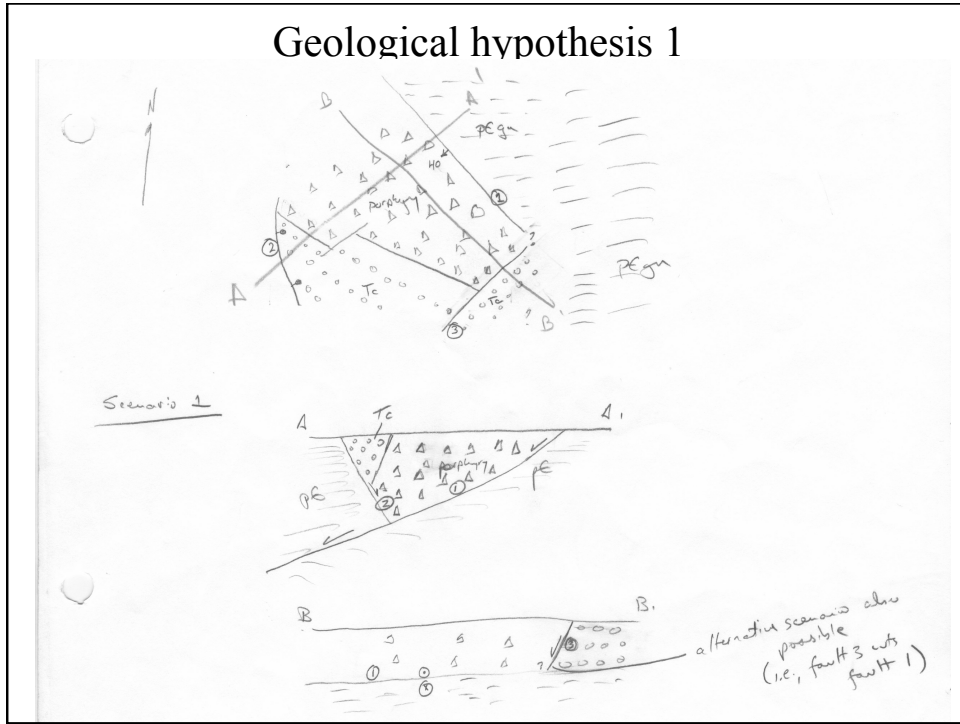
$$r_{ijk} = \sqrt{x_i^2 + y_j^2 + z_k^2}, \mu_{ijk} = (-1)^i (-1)^j (-1)^k$$

Nagy (1966) carried out the integration in formula 2.8 in a different way than Sorokin using arcsine functions instead of arctangent functions:

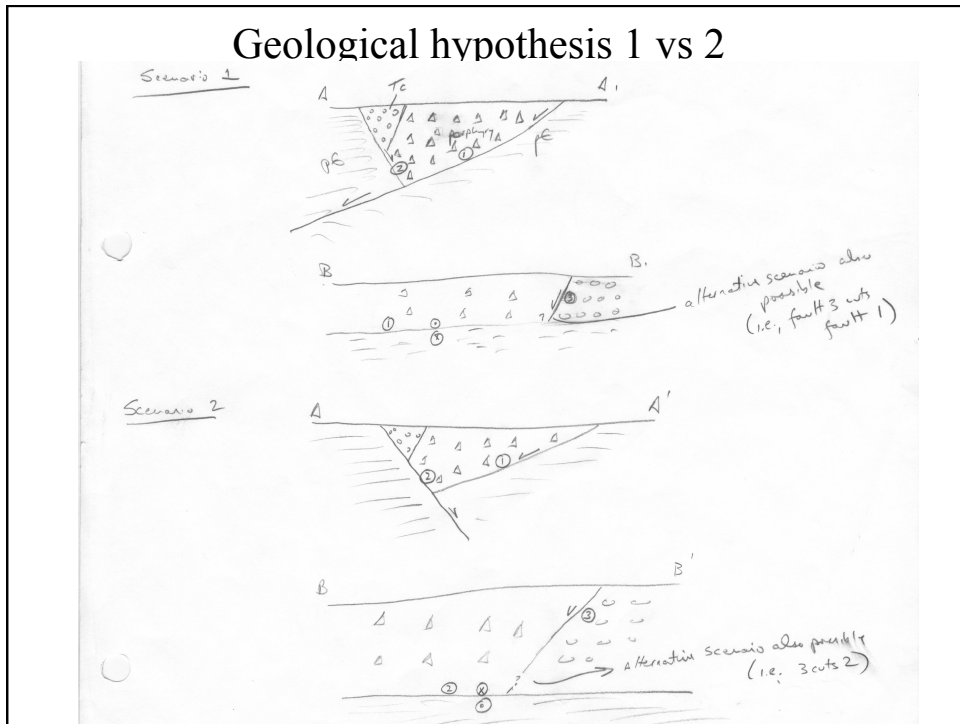
$$g = -f\rho \sum_{i=1}^2 \sum_{j=1}^2 \sum_{k=1}^2 \mu_{ijk} \left[x_i \ln(y_j + r_{ijk}) + y_j \ln(x_i + r_{ijk}) - z_k \arcsin \frac{y_j^2 + z_k^2 + y_j r_{ijk}}{(y_j + r_{ijk}) \sqrt{y_j^2 + z_k^2}} \right] \quad (2.10)$$



Geological hypothesis 1



Geological hypothesis 1 vs 2



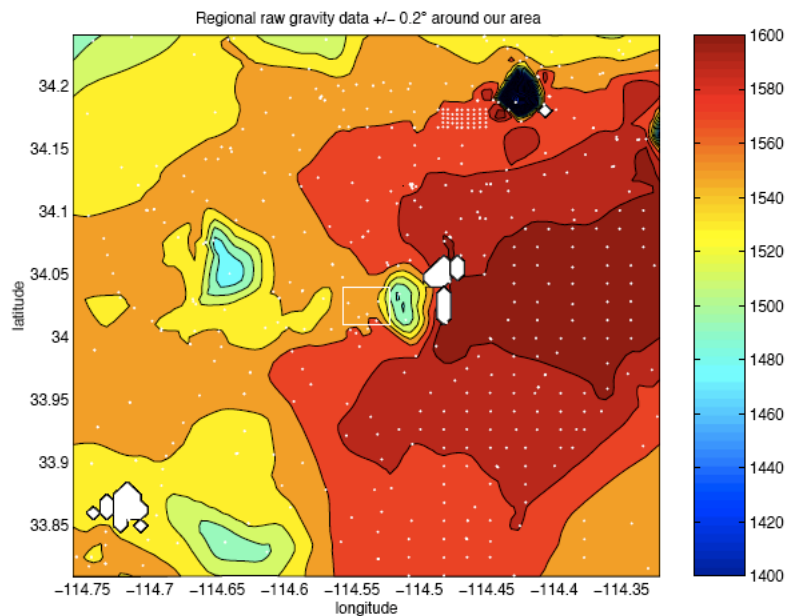
Gravity data: www.scec.org; on web page

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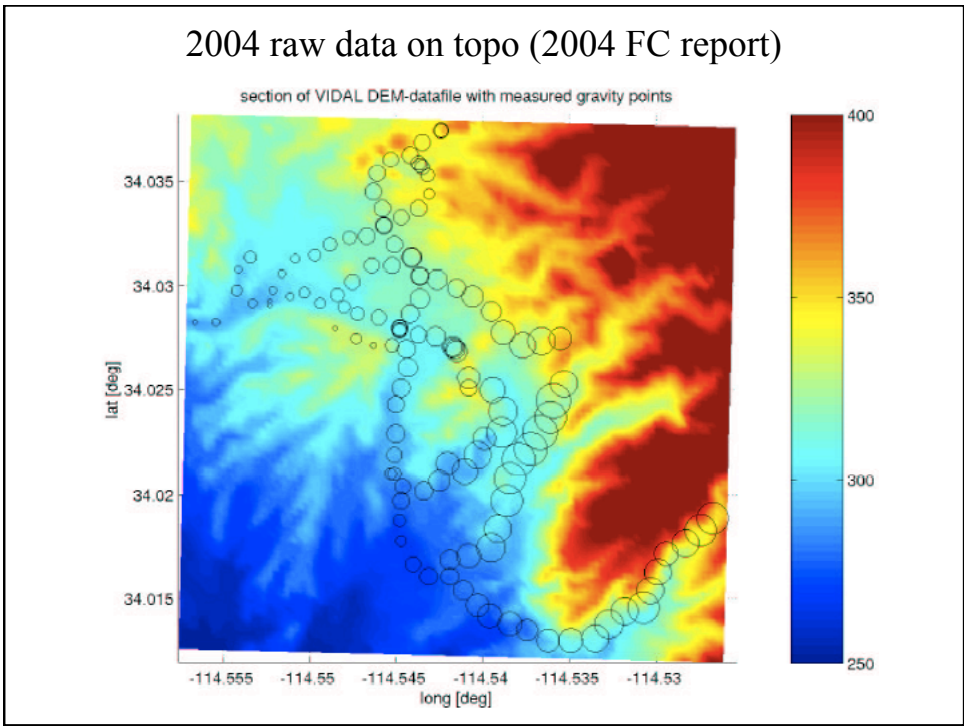
#                               #
# Southern California Gravity Data (point measurements)                #
#                               #
# Contributed to the Southern California Earthquake Center by          #
# Dr. Shawn Biehler of University of California at Riverside           #
# on December 14, 1998.                                             #
#                               #
# Notes:                                                                #
# 0) Stations name used by Shawn Biehler.                              #
# 1) Latitude and longitude were given to 1/100 minute. Here they are given in #
#    decimal degrees.                                                #
# 2) Elevation is given in meters above sea level. Original was in feet. The #
#    column 'E' denotes the method of determining elevation:         #
#    T => original in tenths of feet (method unspecified)           #
#    M => map contour (accuracy 1 foot)                             #
#    B => bench mark (accuracy 1 foot)                             #
#    U => useful (accuracy and method unspecified)                 #
# 3) Raw gravity - 978000.00 mgals (original accuracy 0.01 mgals)   #
# 4) Predicted gravity - 978000.00 mgals, from XXXXX                #
# 5) inT -> inner terrane correction, 0 - 1km box.                  #
#    outT -> outer terrane correction, 1 - 20 km box.              #
#    T -> method of inner terrane correction.                       #
# 6) FAA - Free Air Anomaly (mgals) (original accuracy 0.01 mgals). #
# 7) BOUG - Bouger Anomaly (mgals) (original accuracy 0.01 mgals)  #
# 8) map - quadrangle map location of stations - first 3 letters denote map, #
#    digits indicate site marked on map.                             #
#                               #
# stat lat long elev E Raw g Pred g inT outT T faa boug map #
#-----#
RO2050 34.96100 -119.44650 889.07 T 1494.47 1742.24 0.32 0.97 G 26.59 828.43 BLC_11
RO2048 34.96667 -119.44000 848.84 T 1498.36 1742.72 0.64 1.08 G 17.59 824.35 BLC_12
RO2020 34.95800 -119.43800 922.29 T 1485.64 1741.98 0.32 1.07 G 28.27 826.49 BLC_10

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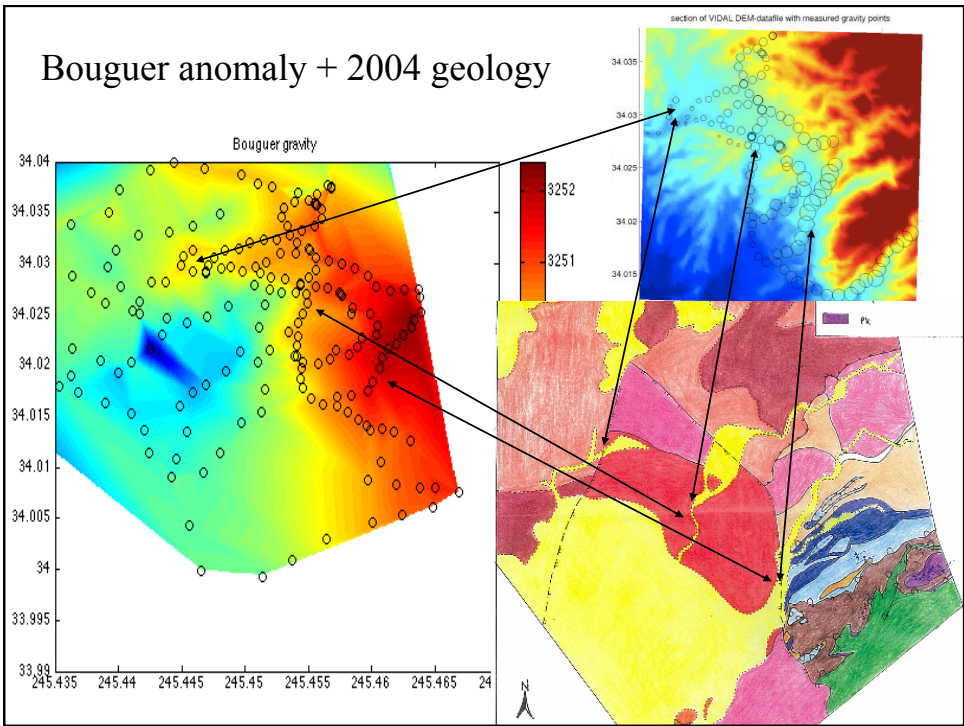
Regional raw data (2004 FC report)



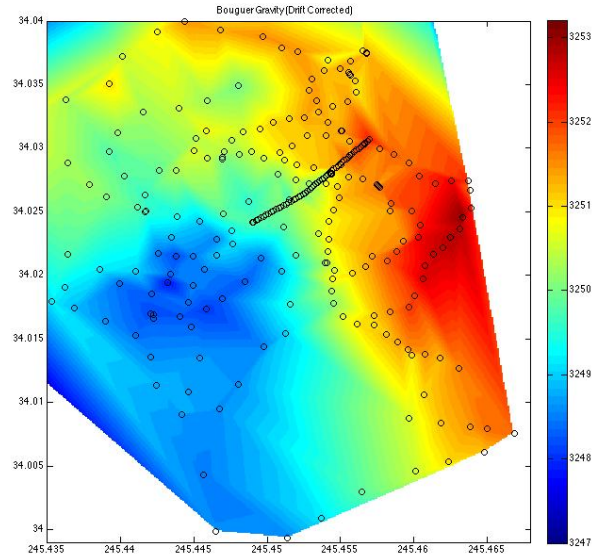
2004 raw data on topo (2004 FC report)



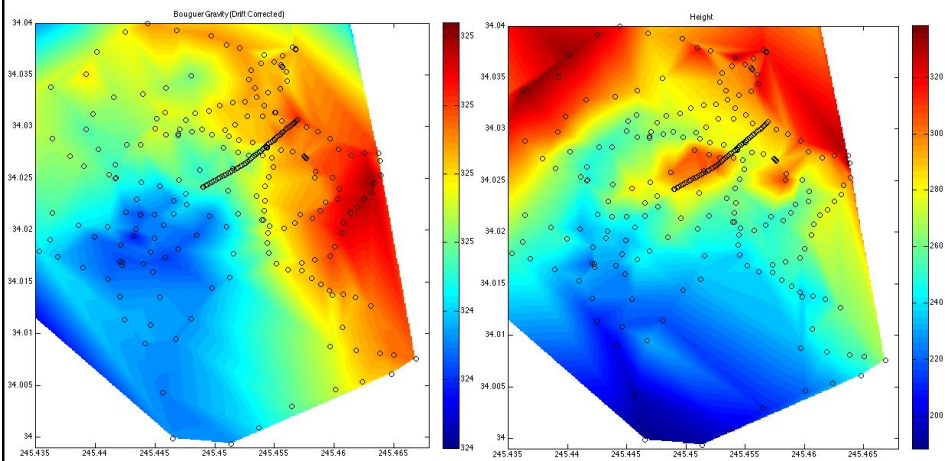
Bouguer anomaly + 2004 geology



Bouguer anomaly, '04, '05, '08



Bouguer anomaly, '04, '05, '08



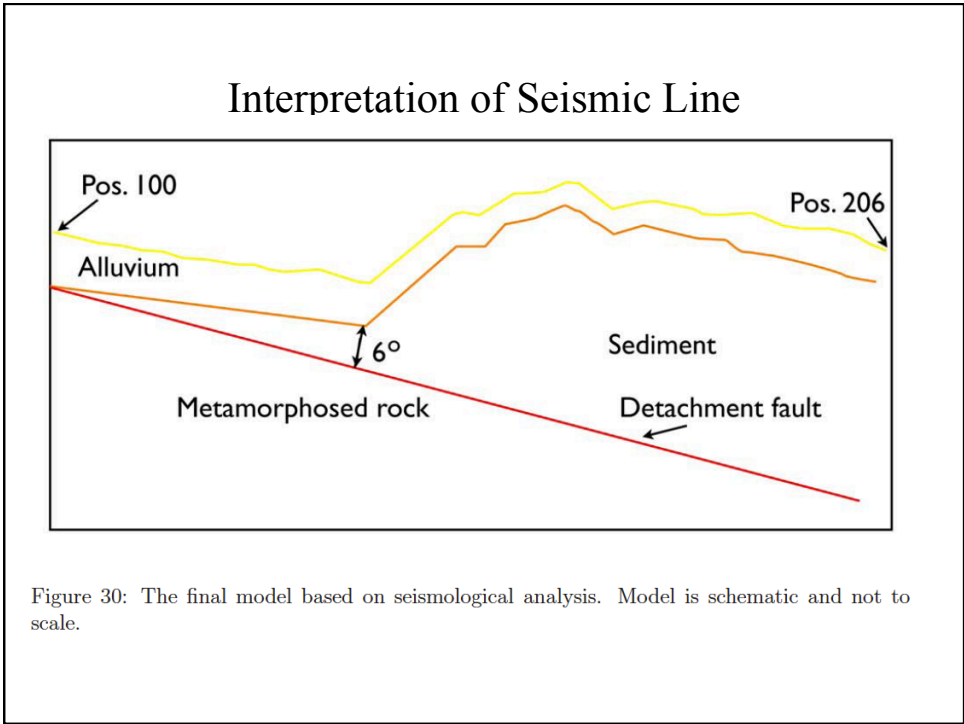
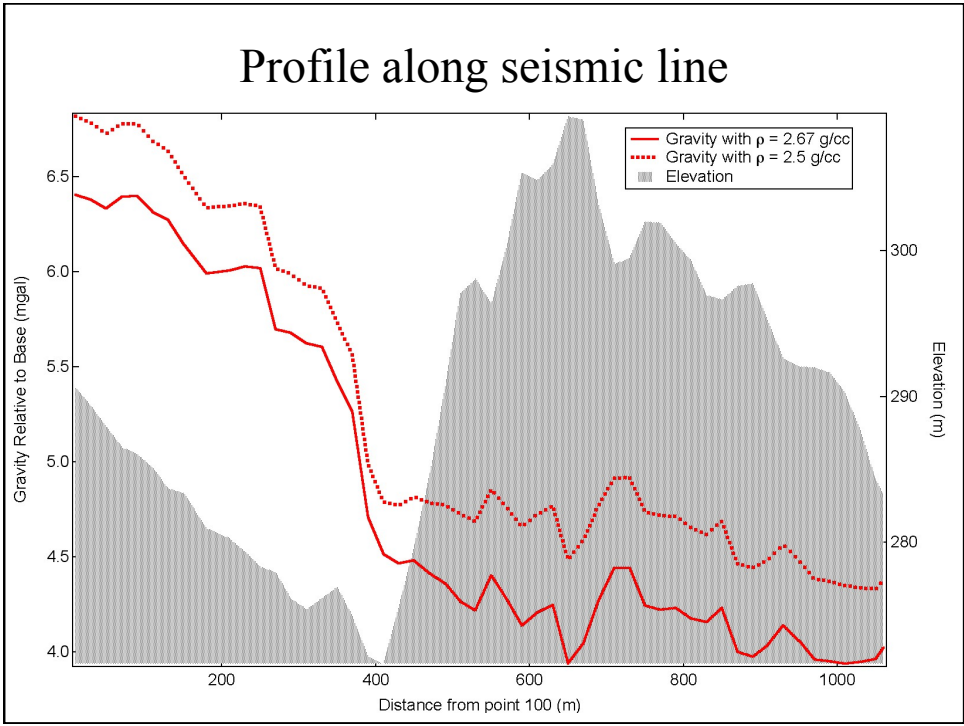


Figure 30: The final model based on seismological analysis. Model is schematic and not to scale.

This year's plan:

- Figure out what measurements would best constrain geologic model
 - Sources of uncertainty
 - Logistical constraints
- Carry out field campaign
- Implement 3-D model

Before leaving:

- 1) Gravimeter practice (all)
- 2) Gravimeter problem set (all)
- 3) Calculate expected dial reading at field camp (all)
- 4) Get tidal corrections (1 person)
- 5) Complete integration 2004, 2005, and 2008 data (1 person)
- 6) DEM(s?) for Vidal quadrangle and vicinity (1 person)